

1.8 Types of topological vector spaces In the following definitions, X always denotes a topological vector space, with topology τ .

- (a) X is *locally convex* if there is a local base \mathcal{B} whose members are convex.
- (b) X is *locally bounded* if 0 has a bounded neighborhood.
- (c) X is *locally compact* if 0 has a neighborhood whose closure is compact.
- (d) X is *metrizable* if τ is compatible with some metric d .
- (e) X is an *F-space* if its topology τ is induced by a complete invariant metric d . (Compare Section 1.25.)
- (f) X is a *Fréchet space* if X is a locally convex *F-space*.
- (g) X is *normable* if a norm exists on X such that the metric induced by the norm is compatible with τ .
- (h) *Normed spaces* and *Banach spaces* have already been defined (Section 1.2).
- (i) X has the *Heine-Borel property* if every closed and bounded subset of X is compact.

The terminology of (e) and (f) is not universally agreed upon: In some texts, local convexity is omitted from the definition of a Fréchet space, whereas others use *F-space* to describe what we have called Fréchet space.

1.9 Here is a list of some relations between these properties of a topological vector space X .

- (a) If X is locally bounded, then X has a countable local base [part (c) of Theorem 1.15].
- (b) X is metrizable if and only if X has a countable local base (Theorem 1.24).
- (c) X is normable if and only if X is locally convex and locally bounded (Theorem 1.39).
- (d) X has finite dimension if and only if X is locally compact (Theorems 1.21, 1.22).
- (e) If a locally bounded space X has the Heine-Borel property, then X has finite dimension (Theorem 1.23).

1.13 Theorem *Let X be a topological vector space.*

- (a) *If $A \subset X$ then $\bar{A} = \bigcap (A + V)$, where V runs through all neighborhoods of 0.*
- (b) *If $A \subset X$ and $B \subset X$, then $\bar{A} + \bar{B} \subset \overline{A + B}$.*
- (c) *If Y is a subspace of X , so is \bar{Y} .*
- (d) *If C is a convex subset of X , so are \bar{C} and C° .*
- (e) *If B is a balanced subset of X , so is \bar{B} ; if also $0 \in B^\circ$ then B° is balanced.*
- (f) *If E is a bounded subset of X , so is \bar{E} .*

PROOF. (a) $x \in \bar{A}$ if and only if $(x + V) \cap A \neq \emptyset$ for every neighborhood V of 0, and this happens if and only if $x \in A - V$ for every such V . Since $-V$ is a neighborhood of 0 if and only if V is one, the proof is complete.

(b) Take $a \in \bar{A}$, $b \in \bar{B}$; let W be a neighborhood of $a + b$. There are neighborhoods W_1 and W_2 of a and b such that $W_1 + W_2 \subset W$. There exist $x \in A \cap W_1$ and $y \in B \cap W_2$, since $a \in \bar{A}$ and $b \in \bar{B}$. Then $x + y$ lies in $(A + B) \cap W$, so that this intersection is not empty. Consequently, $a + b \in \overline{A + B}$.

(c) Suppose α and β are scalars. By the proposition in Section 1.7, $\alpha\bar{Y} = \overline{\alpha Y}$ if $\alpha \neq 0$; if $\alpha = 0$, these two sets are obviously equal. Hence it follows from (b) that

$$\alpha\bar{Y} + \beta\bar{Y} = \overline{\alpha Y} + \overline{\beta Y} \subset \overline{\alpha Y + \beta Y} \subset \bar{Y};$$

the assumption that Y is a subspace was used in the last inclusion.

The proofs that convex sets have convex closures and that balanced sets have balanced closures are so similar to this proof of (c) that we shall omit them from (d) and (e).

1.14 Theorem *In a topological vector space X ,*

- (a) *every neighborhood of 0 contains a balanced neighborhood of 0, and*
- (b) *every convex neighborhood of 0 contains a balanced convex neighborhood of 0.*

PROOF. (a) Suppose U is a neighborhood of 0 in X . Since scalar multiplication is continuous, there is a $\delta > 0$ and there is a neighborhood V of 0 in X such that $\alpha V \subset U$ whenever $|\alpha| < \delta$. Let W be the union of all these sets αV . Then W is a neighborhood of 0, W is balanced, and $W \subset U$.

Corollary

- (a) *Every topological vector space has a balanced local base.*
- (b) *Every locally convex space has a balanced convex local base.*

Suppose now that X and Y are vector spaces over the same scalar field. A mapping $\Lambda: X \rightarrow Y$ is said to be *linear* if

$$\Lambda(\alpha x + \beta y) = \alpha \Lambda x + \beta \Lambda y$$

for all x and y in X and all scalars α and β . Note that one often writes Λx , rather than $\Lambda(x)$, when Λ is linear.

Linear mappings of X into its scalar field are called *linear functionals*.

Here are some properties of linear mappings $\Lambda: X \rightarrow Y$ whose proofs are so easy that we omit them; it is assumed that $A \subset X$ and $B \subset Y$:

- (a) $\Lambda 0 = 0$.
- (b) If A is a subspace (or a convex set, or a balanced set) the same is true of $\Lambda(A)$.
- (c) If B is a subspace (or a convex set, or a balanced set) the same is true of $\Lambda^{-1}(B)$.
- (d) In particular, the set

$$\Lambda^{-1}(\{0\}) = \{x \in X: \Lambda x = 0\} = \mathcal{N}(\Lambda)$$

is a subspace of X , called the *null space* of Λ .

1.18 Theorem *Let Λ be a linear functional on a topological vector space X . Assume $\Lambda x \neq 0$ for some $x \in X$. Then each of the following four properties implies the other three:*

- (a) Λ is continuous.
- (b) The null space $\mathcal{N}(\Lambda)$ is closed.
- (c) $\mathcal{N}(\Lambda)$ is not dense in X .
- (d) Λ is bounded in some neighborhood V of 0.

PROOF. Since $\mathcal{N}(\Lambda) = \Lambda^{-1}(\{0\})$ and $\{0\}$ is a closed subset of the scalar field Φ , (a) implies (b). By hypothesis, $\mathcal{N}(\Lambda) \neq X$. Hence (b) implies (c).

Assume (c) holds; i.e., assume that the complement of $\mathcal{N}(\Lambda)$ has nonempty interior. By Theorem 1.14,

$$(1) \quad (x + V) \cap \mathcal{N}(\Lambda) = \emptyset$$

for some $x \in X$ and some balanced neighborhood V of 0. Then ΛV is a balanced subset of the field Φ . Thus either ΛV is bounded, in which case (d) holds, or $\Lambda V = \Phi$. In the latter case, there exists $y \in V$ such that $\Lambda y = -\Lambda x$, and so $x + y \in \mathcal{N}(\Lambda)$, in contradiction to (1). Thus

Finite-Dimensional Spaces

1.19 Among the simplest Banach spaces are R^n and \mathcal{C}^n , the standard n -dimensional vector spaces over R and \mathcal{C} , respectively, normed by means of the usual euclidean metric: If, for example,

$$z = (z_1, \dots, z_n) \quad (z_i \in \mathcal{C})$$

is a vector in \mathcal{C}^n , then

$$\|z\| = (|z_1|^2 + \dots + |z_n|^2)^{1/2}.$$

Other norms can be defined on \mathcal{C}^n . For example,

$$\|z\| = |z_1| + \dots + |z_n| \quad \text{or} \quad \|z\| = \max (|z_i| : 1 \leq i \leq n).$$

These norms correspond, of course, to different metrics on \mathcal{C}^n (when $n > 1$) but one can see very easily that they all induce the same topology on \mathcal{C}^n . Actually, more is true.

If X is a topological vector space over \mathbb{C} , and $\dim X = n$, then every basis of X induces an isomorphism of X onto \mathbb{C}^n . Theorem 1.21 will prove that this *isomorphism must be a homeomorphism*. In other words, this says that *the topology of \mathbb{C}^n is the only vector topology that an n -dimensional complex topological vector space can have*.

We shall also see that finite-dimensional subspaces are always closed and that no infinite-dimensional topological vector space is locally compact.

Everything in the preceding discussion remains true with real scalars in place of complex ones.

1.20 Lemma *If X is a complex topological vector space and $f: \mathbb{C}^n \rightarrow X$ is linear, then f is continuous.*

PROOF. Let $\{e_1, \dots, e_n\}$ be the standard basis of \mathbb{C}^n : The k th coordinate of e_k is 1, the others are 0. Put $u_k = f(e_k)$, for $k = 1, \dots, n$. Then $f(z) = z_1 u_1 + \dots + z_n u_n$ for every $z = (z_1, \dots, z_n)$ in \mathbb{C}^n . Every z_k is a continuous function of z . The continuity of f is therefore an immediate consequence of the fact that addition and scalar multiplication are continuous in X . ////

1.21 Theorem *If n is a positive integer and Y is an n -dimensional subspace of a complex topological vector space X , then*

- (a) *every isomorphism of \mathbb{C}^n onto Y is a homeomorphism, and*
- (b) *Y is closed.*

1.22 Theorem *Every locally compact topological vector space X has finite dimension.*

PROOF. The origin of X has a neighborhood V whose closure is compact. By Theorem 1.15, V is bounded, and the sets $2^{-n}V$ ($n = 1, 2, 3, \dots$) form a local base for X .

The compactness of \bar{V} shows that there exist x_1, \dots, x_m in X such that

$$\bar{V} \subset (x_1 + \tfrac{1}{2}V) \cup \dots \cup (x_m + \tfrac{1}{2}V).$$

Let Y be the vector space spanned by x_1, \dots, x_m . Then $\dim Y \leq m$. By Theorem 1.21, Y is a *closed* subspace of X .

Since $V \subset Y + \tfrac{1}{2}V$ and since $\lambda Y = Y$ for every scalar $\lambda \neq 0$, it follows that

$$\tfrac{1}{2}V \subset Y + \tfrac{1}{4}V$$

so that

$$V \subset Y + \tfrac{1}{2}V \subset Y + Y + \tfrac{1}{4}V = Y + \tfrac{1}{4}V.$$

If we continue in this way, we see that

$$V \subset \bigcap_{n=1}^{\infty} (Y + 2^{-n}V).$$

Since $\{2^{-n}V\}$ is a local base, it now follows from (a) of Theorem 1.13 that $V \subset \bar{Y}$. But $\bar{Y} = Y$. Thus $V \subset Y$, which implies that $kV \subset Y$ for $k = 1, 2, 3, \dots$. Hence $Y = X$, by (a) of Theorem 1.15, and consequently $\dim X \leq m$. ////

1.23 Theorem *If X is a locally bounded topological vector space with the Heine-Borel property, then X has finite dimension.*

PROOF. By assumption, the origin of X has a bounded neighborhood V . Statement (f) of Theorem 1.13 shows that \bar{V} is also bounded. Thus \bar{V} is compact, by the Heine-Borel property. This says that X is locally compact, hence finite-dimensional, by Theorem 1.22.

References:

1. Robertson, W. Topological vector spaces. CUP Archive, Vol. 53, 1980.
2. Bourbaki, N. Topological vector spaces: Chapters 1–5. Springer Science and Business Media, 2013.
3. Bogachev, V. I., Smolyanov, O. G., Sobolev. Topological vector spaces and their applications. Springer, Vol. 1, 2017.

4. Rudin, W. Functional analysis, mir, 1975.