Chapter one *The vectors*

1-1 physical Quantities

Scalar quantity: the quantity that is completely specified by a number and appropriate units, such as Temperature, mass, time,.....etc.

Vector quantity: is a physical quantity that is completely specified by a number and appropriate units plus a direction in which it is affect, such as displacement, velocity, acceleration, force,....etc.

Let \vec{A} a vector, it's magnitude |A|, and \hat{n} is the unit vector defined as a dimensionless vector having a magnitude of exactly (1). Then we can write the vector \vec{A} as:

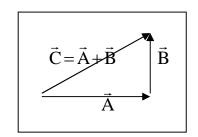
$$\vec{A} = \hat{n} |A|$$
 $\vec{A} = \hat{n} |A|$

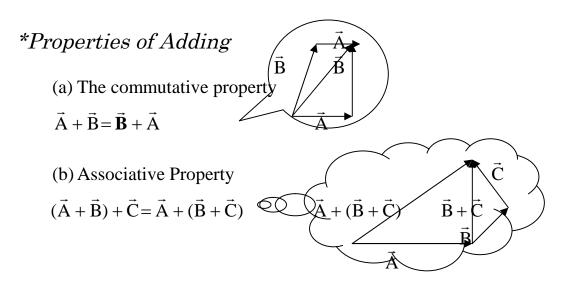
1-2 Multiplying a Vector by a Scalar

If \vec{A} a vector multiplied by a scalar quantity (n) then $(n\vec{A})$ is the vector has the same direction of \vec{A} and magnitude (n A).

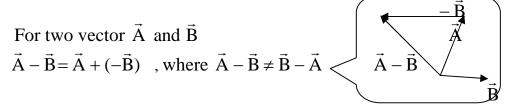
1-3 Adding Vectors

Draw vector \vec{A} , then draw vector \vec{B} write it's tail starting from the tip of \vec{B} . The vector \vec{C} is the resultant of adding \vec{A} and \vec{B} . The resultant \vec{C} is the vector drawn from the tail of \vec{A} to the tip of \vec{B} .





1-4 Subtracting Vectors



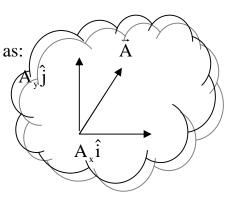
1-5 Vectors Analysis

We use the symbols i, j and k to represent unit vectors in the position x, y and z direction respectively. The magnitude of each unit vector equals unity, that is

$$|i| = |j| = |k| = 1$$

In xy-plane , we represent the vector \vec{A} as:

$$\vec{A} = A_x \hat{i} + A_y \hat{j}$$



For \vec{A} , \vec{B} are two vectors, where

 $\vec{A} = A_x \hat{i} + A_y \hat{j}$, $\vec{B} = B_x \hat{i} + B_y \hat{j}$

The resultant of \vec{A} and \vec{B} is R

$$R = \vec{A} + \vec{B} = (A_x \hat{i} + A_y \hat{j}) + (B_x \hat{i} + B_y \hat{j})$$

 $R = (A_x + B_x)\hat{i} + (A_y + B_y)\hat{j}$

Then, the component of the resultant R are:

 $R_x = A_x + B_y \qquad , R_y = A_y + B_y$

Then the magnitude of the resultant R and it's direction are written as:

$$R = \sqrt{R_{x}^{2} + R_{y}^{2}} = \sqrt{(A_{x} + B_{x})^{2} + (A_{y} + B_{y})^{2}}$$

And

$$\tan \theta = \frac{R_y}{R_x}$$
 or $\theta = \tan^{-1} \frac{R_y}{R_x}$

Now, for \vec{A} and \vec{B} are two vectors have x , y and z components, we express these vectors in the form :

 $\vec{\mathbf{A}} = \mathbf{A}_{x}\hat{\mathbf{i}} + \mathbf{A}_{y}\hat{\mathbf{j}} + \mathbf{A}_{z}\hat{\mathbf{k}}$ $\vec{\mathbf{B}} = \mathbf{B}_{x}\hat{\mathbf{i}} + \mathbf{B}_{y}\hat{\mathbf{j}} + \mathbf{B}_{z}\hat{\mathbf{k}}$

And the resultant R of the vectors is:

$$R = \vec{A} + \vec{B} = (A_{x} + B_{x})\hat{i} + (A_{y} + B_{y})\hat{j} + (A_{z} + B_{z})\hat{k}$$